



The Geodetic Networks & Space Geodesy Applications

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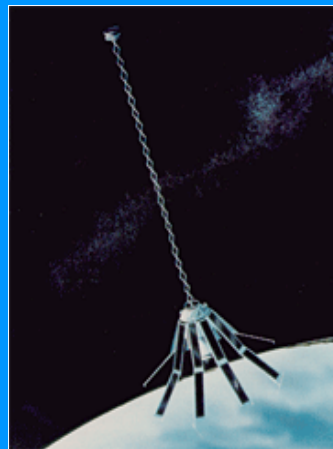
From the launch of the first spaceborne altimeters, Precision Orbit Determination (POD) has been driven by the science goals of the geodetic altimeter missions...



GEOS-3, 1975



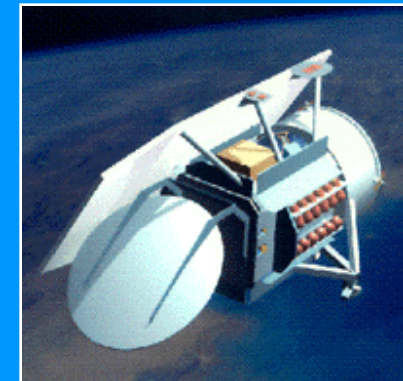
SEASAT, 1978



GEOSAT, 1985



**TOPEX/POSEIDON,
1992**



**GFO-1,
1998**



**Jason-1, 2002
Jason-2, 2008**



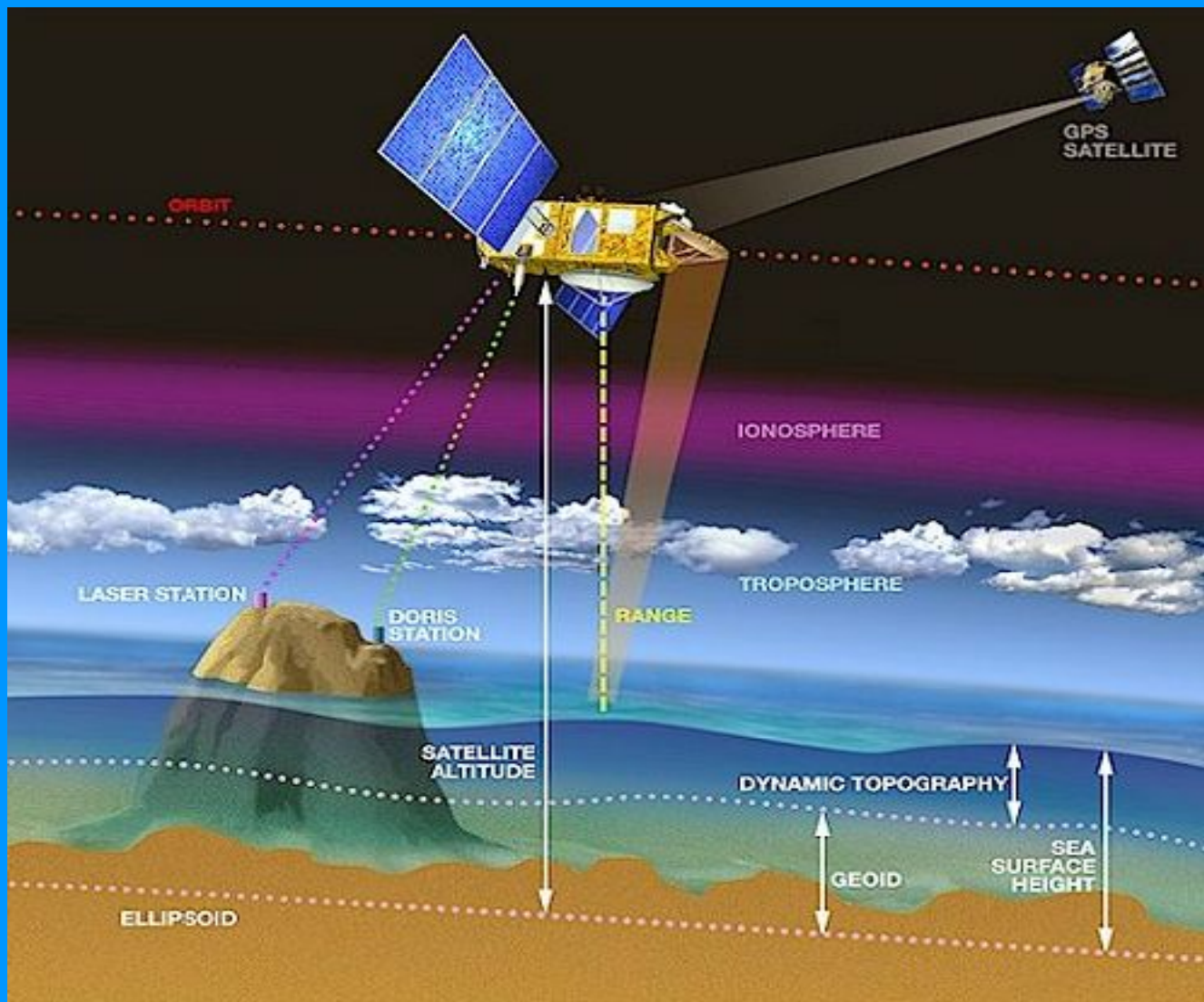
ENVISAT, 2002



CRYOSAT-2, 2010

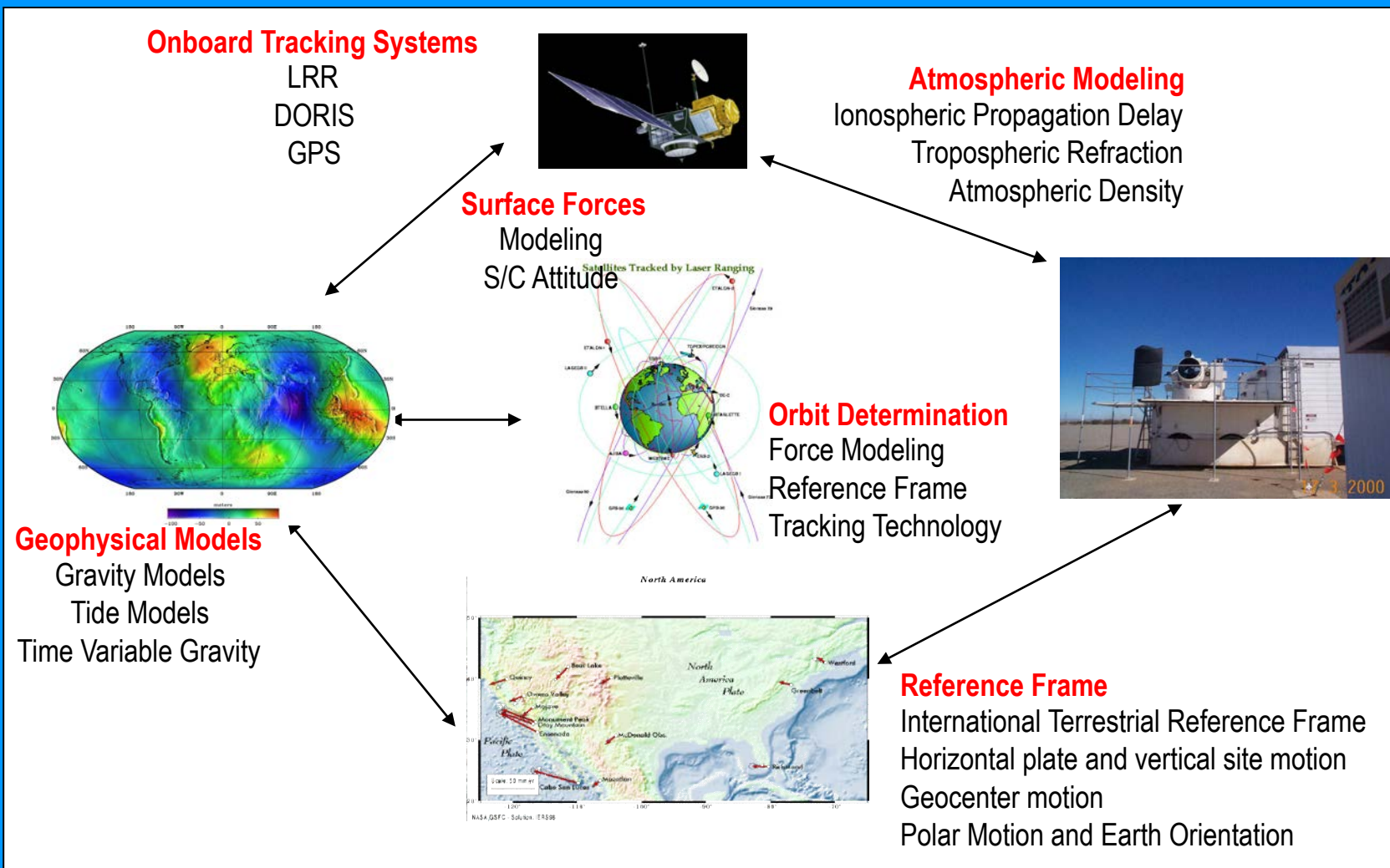


POD Schematic





Orbit Determination Schematic





Force models



I. Gravity.

$$U = \frac{GM}{r} + \frac{GM}{r} \sum_{n=2}^{\infty} \sum_{m=0}^n \left(\frac{a_e}{r}\right)^n \bar{P}_{nm}(\sin \phi) \\ \times [\bar{C}_{nm} \cos m\lambda + \bar{S}_{nm} \sin m\lambda],$$

II. Solar radiation pressure

III. Planetary radiation pressure (albedo & thermal emission).

(Cannonball, Macromodel, box-wing ...)

IV. Atmospheric drag.

V. Earth Solid tides & Ocean Tides.

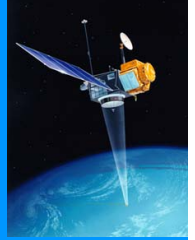
VI. Third body (Sun, Moon, Planets)

VII. Relativity.

.....



Measurement modelling



- I. Coordinate System
- II. Tracking station coordinates.
 - Earth solid tide effects.
 - Ocean loading effects.
- III. Earth orientation parameters.
- IV. Media effects.
 - Earth troposphere refraction.
 - Ionosphere (radio frequencies)
- V. Relativity.
 - Range delay; Light time; Coordinate-> Atomic time.
- VI. Planetary ephemerides (DE403...)
- VII. Spacecraft corrections to s/c center of mass.
- VIII. Antenna corrections (phase center variations, motion)

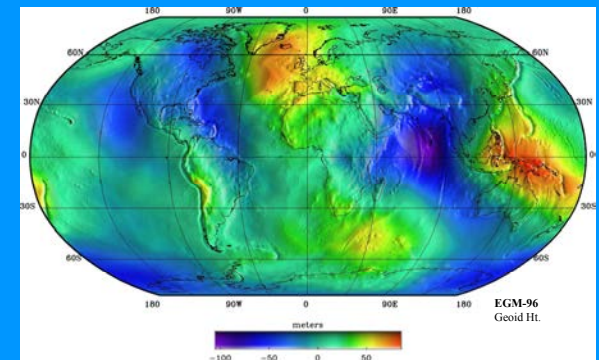


Errors in Models of the Earth's Gravity Field were the largest source of orbit error for altimeter missions ... Until the launch of TOPEX/Poseidon



Model	Radial Calibration (cm)	SLR rms fit (cm)
GEM-L2: 1982	65.4	105.9
GEM-T1: 1988	25.0	31.4
GEM-T2: 1990	10.2	17.8
JGM-1S: 1991	6.0	7.7
JGM-2S: 1992	2.9	4.0
JGM-2: 1992	2.2	3.8
JGM-3: 1995	0.9	3.2
EGM-96 1997	0.8	2.8

GEM-L2: 20x20
JGM1-3: 70x70
EGM96S: 70x70; (360x360)
EIGEN-GL04S: 150x150



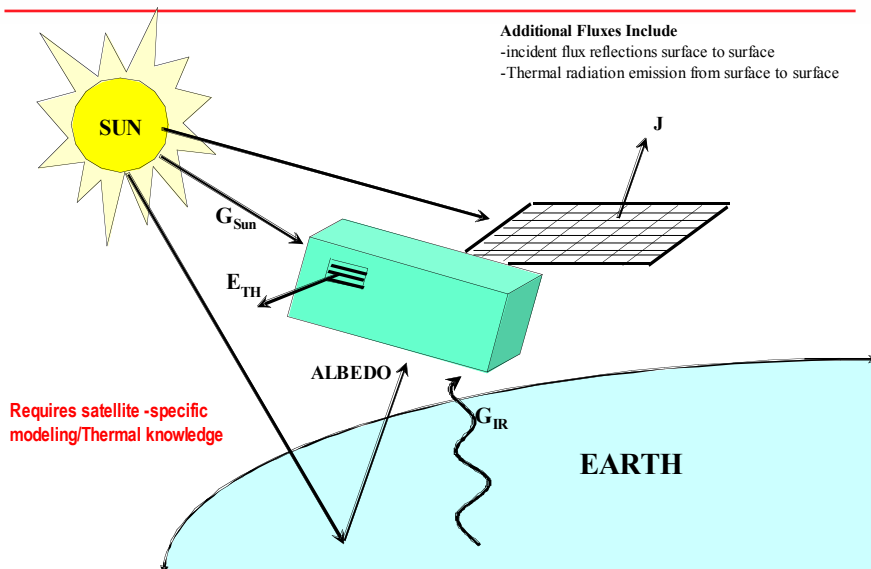
The latest gravity models (e.g. GGM03S, EIGEN-GL04S) derived from GRACE data eliminate static gravity error on the TP orbit and allow us to model in detail the temporal gravity variations



Radiation Pressure Modelling is the largest source of orbit error after gravity model error And remains a challenge



Radiative Fluxes



Micromodel: (Antreasian, 1992;
Antreasian & Rosborough, 1992)

Box-Wing model

(Marshall & Luthcke, 1994)

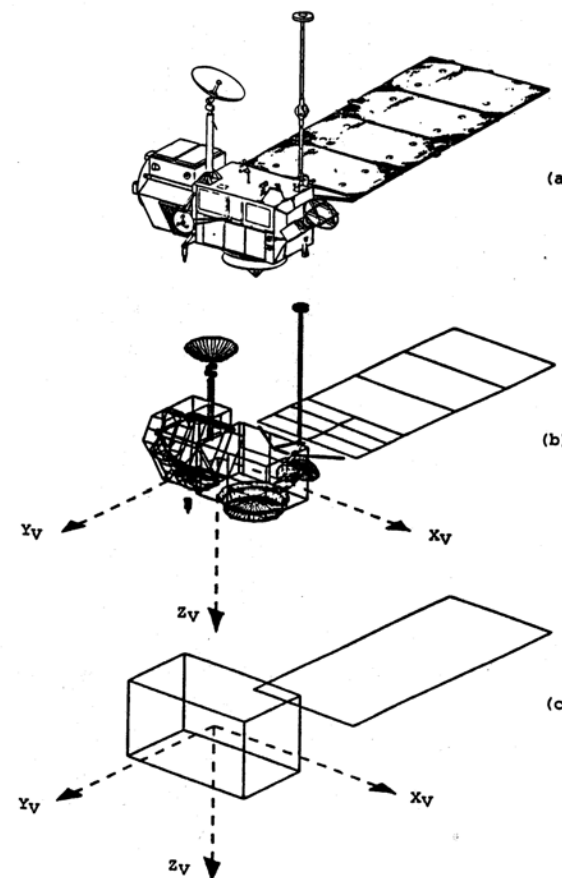


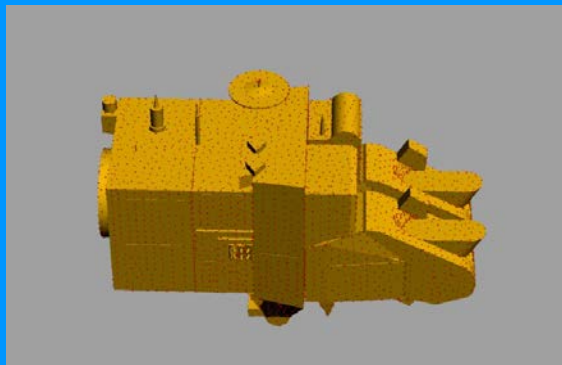
Figure 1. (a) The TOPEX/Poseidon Spacecraft, (b) Micro-Model Approximation, (c) Macro-Model Approximation



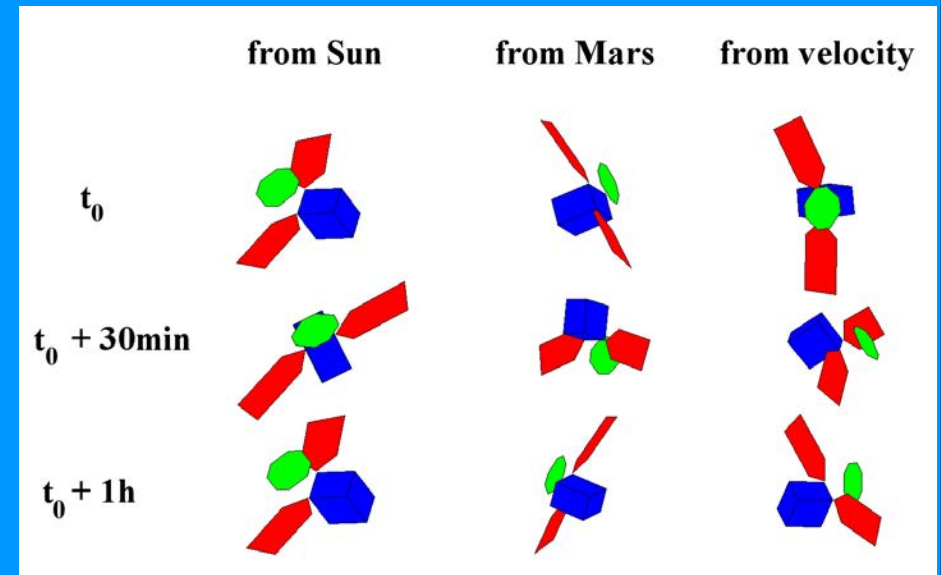
Radiation Pressure Modelling Improvement Strategies (1)



University College London models for LEO spacecraft?



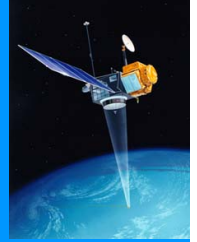
Self-shadowing as in *Mazarico et al., 2009, J. Spacecraft Rockets*, for MRO?



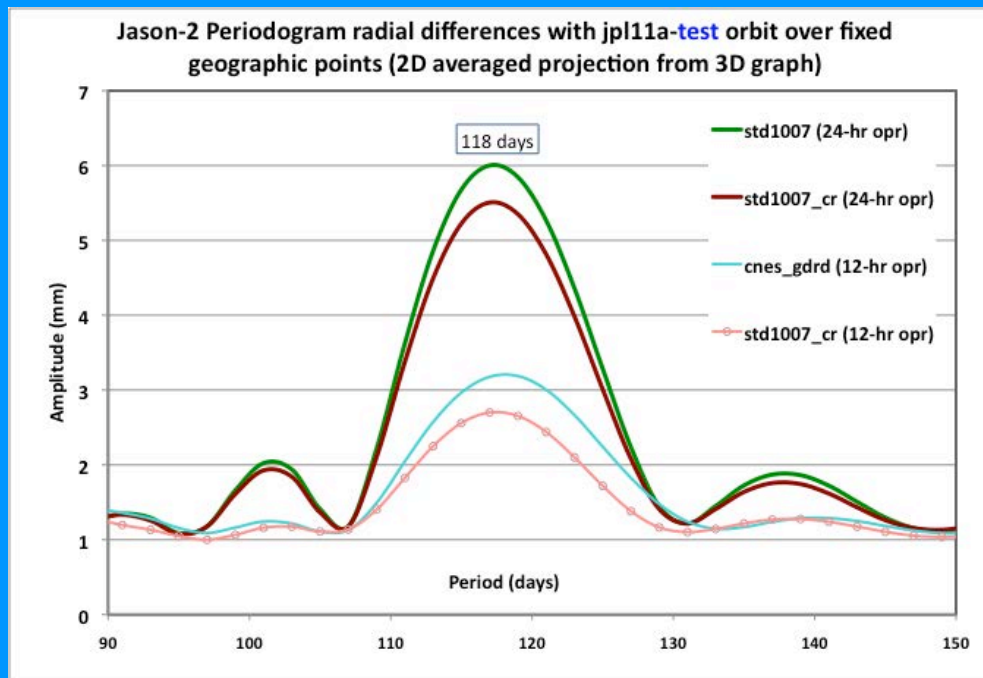
Spacecraft attitude at three different orbital positions - view from different directions.



Radiation Pressure Modelling Improvement Strategies: Adjust Empirical Accelerations (2)



Adjust once-per-revolution empirical
accelerations (along-track, cross-track to orbit)
 $OPR = A \cos wt + B \sin wt$





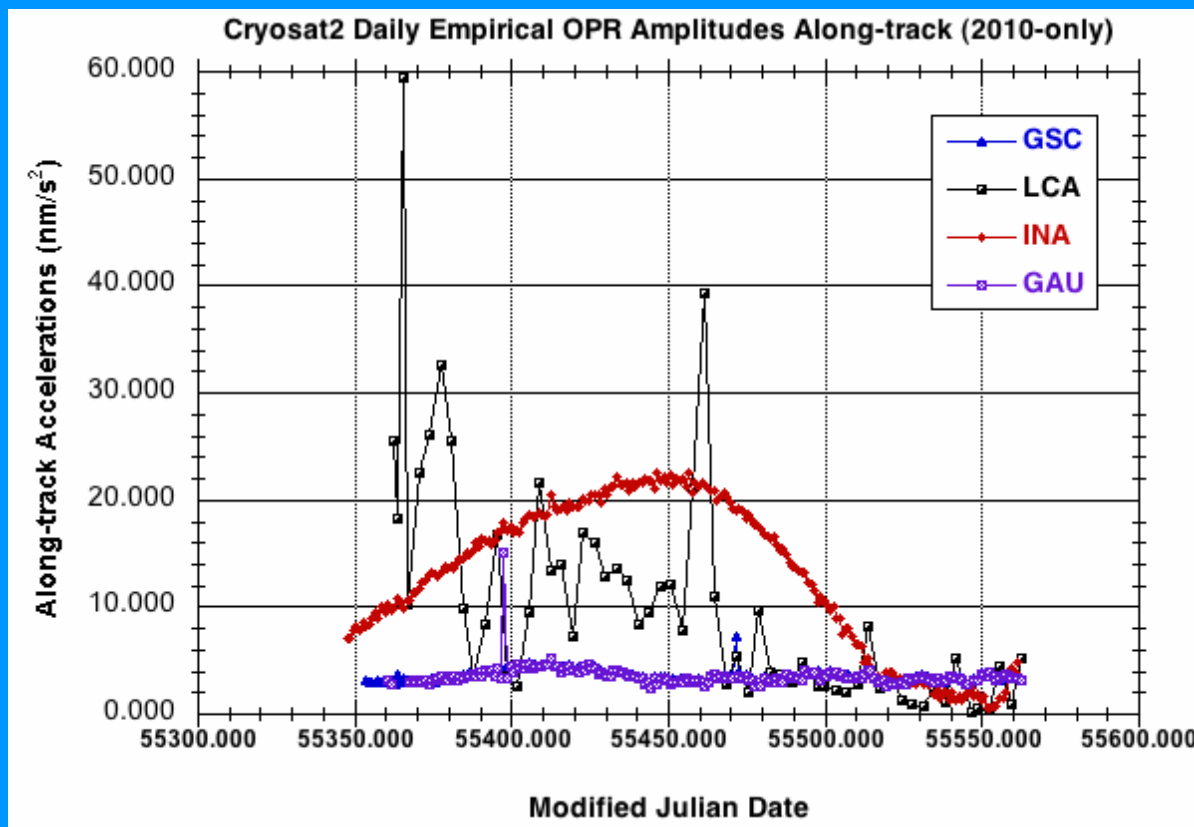
IDS Analysis Center Comparison: Cryosat2 OPR Empirical Acceleration Amplitudes (2010 only)



Doris Center	No. of accels	Alg (avg/median) x 1e09	Crs (avg/median) x 1e09	Adjust period (days)
GSC	208	3.61 / 3.54	2.57 / 2.48	1
ESA	217	2.79 / 2.68	2.92 / 2.77	1
GAU	193	3.51 / 3.43	2.97 / 2.81	1
IGN	214	12.94 / 14.03	7.00 / 5.75	1
INA	214	13.92 / 13.86	6.93 / 4.86	1
LCA	58	9.42 / 7.61	3.41 / 2.76	3.5
CNES POD	247	4.81 / 4.83	3.01 / 2.74	1



IDS Analysis Center Comparison: Cryosat2 OPR Empirical Acceleration Amplitudes (2010 only)





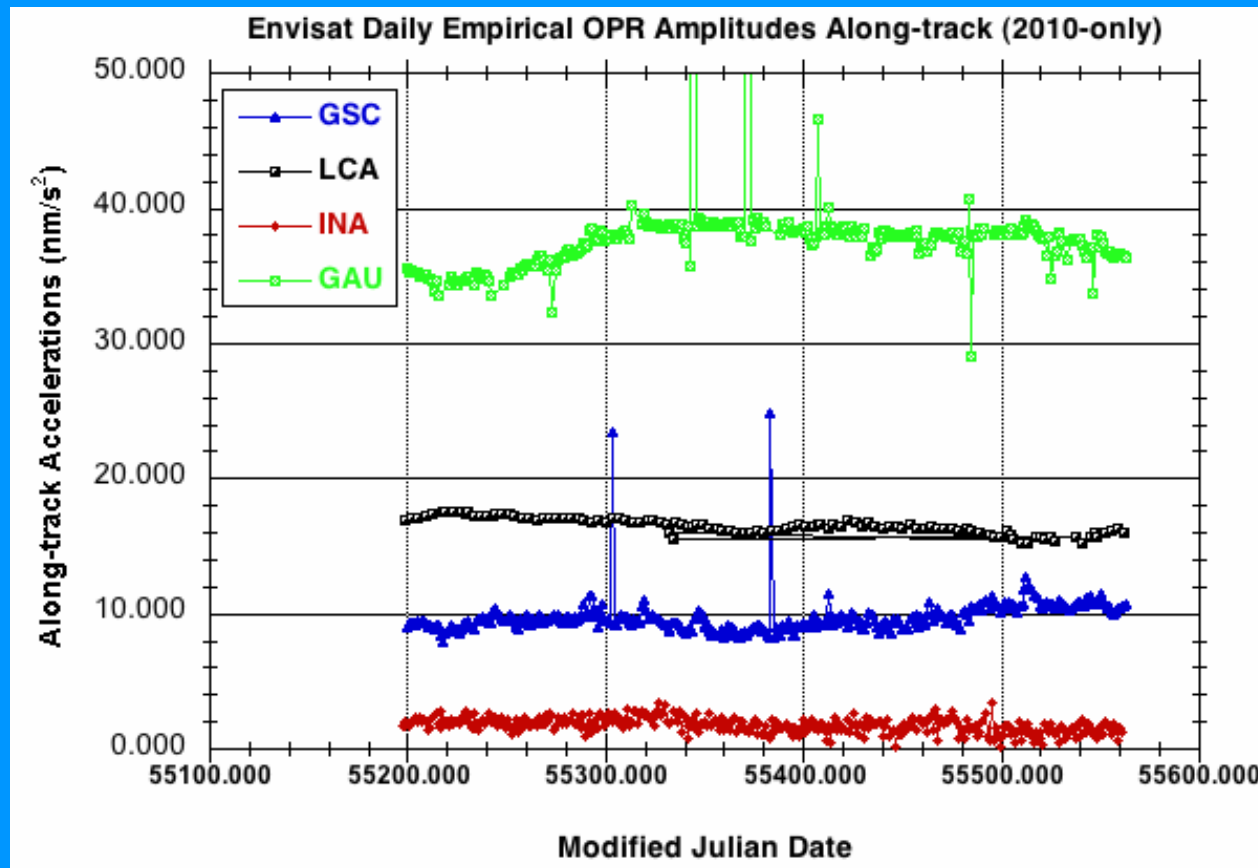
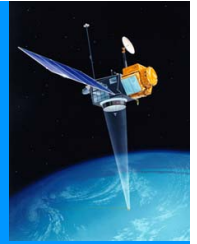
IDS Analysis Center Comparison: Envisat OPR Empirical Acceleration Amplitudes (2010 only)



Doris Center	No. of accels	Alg (avg/median) x 1e09	Crs (avg/median) x 1e09	Adjust period (days)
GSC	355	9.54 / 9.42	2.27 / 2.24	1
ESA	359	1.64 / 1.52	1.89 / 1.71	1
GAU	316	37.39 / 37.88	6.11 / 5.85	1
IGN	365	1.86 / 1.84	2.81 / 2.58	1
INA	364	1.79 / 1.81	23.84 / 23.95	1
LCA	117	16.52 / 16.46	5.33 / 4.98	3.5
CNES POD	416	1.54 / 1.56	1.80 / 1.71	1



IDS Analysis Center Comparison: Envisat OPR Empirical Acceleration Amplitudes (2010 only)





The Geodetic Networks are the Key to Altimeter Satellite Mission Success



Satellite Laser Ranging (SLR)

SLR, Maui

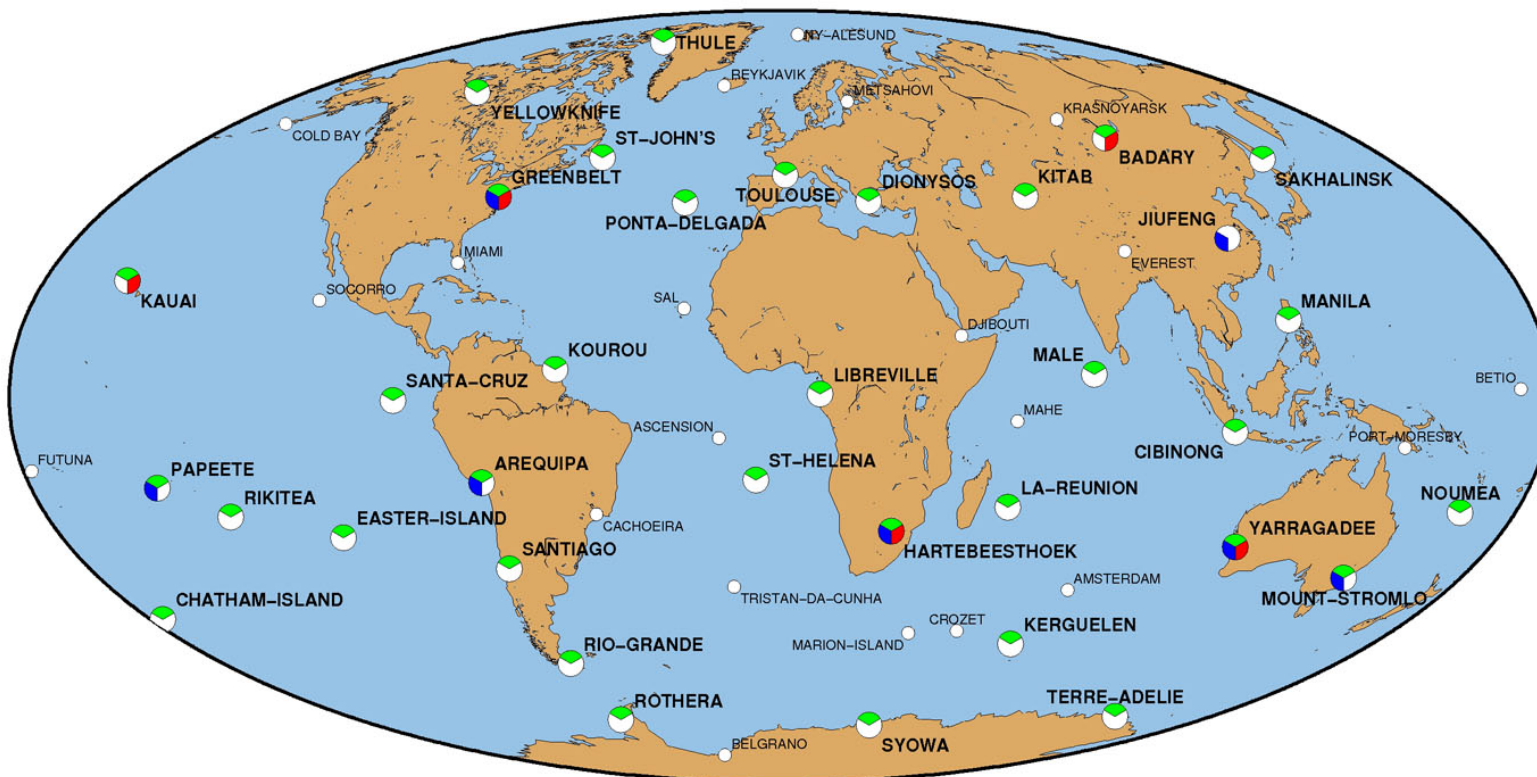


SLR, Graz, Austria





DORIS (Ground Network) (Sept. 2011)



● GNSS (IGS)

● SLR

● VLBI

○ No active co-location < 1 km

2011 Nov 07 09:37:53



Space Geodesy Applications, June 7, 2012

*International
DORIS
Service*



DORIS Station Examples



Rothera, *Antarctica*

- ROTA 1993-2005
- ROTB 2005-2007
- ROUB 2007-present



Thule, *Greenland*

- THUB 2002-present



Arequipa, *Peru*

- AREA 1988-2001
- AREB 2001-2006
- ARFB 2006-present



Space Geodesy Applications, June 7, 2012

**International
DORIS
Service**



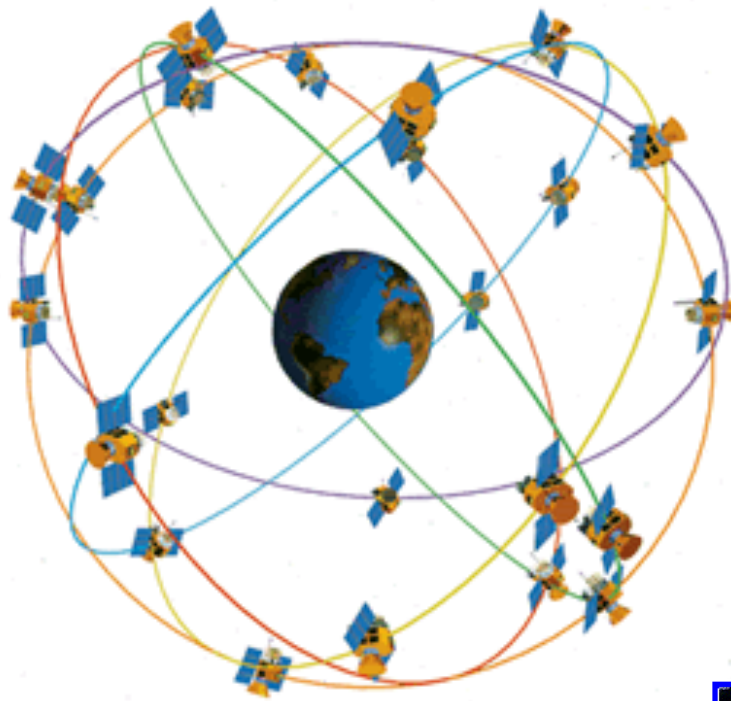
GPS Tracking System for OSTM



International GNSS Service
Formerly the International GPS Service



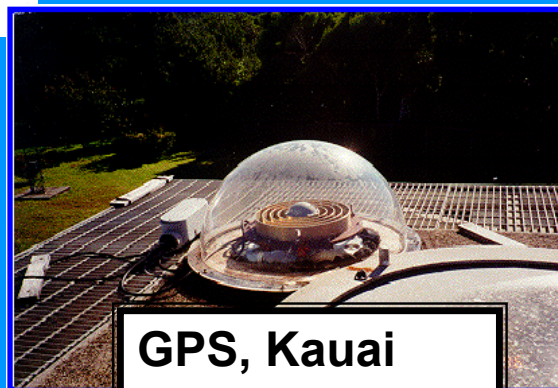
GPS Satellite Constellation



JASON GPS Receiver



Examples: Ground Receivers



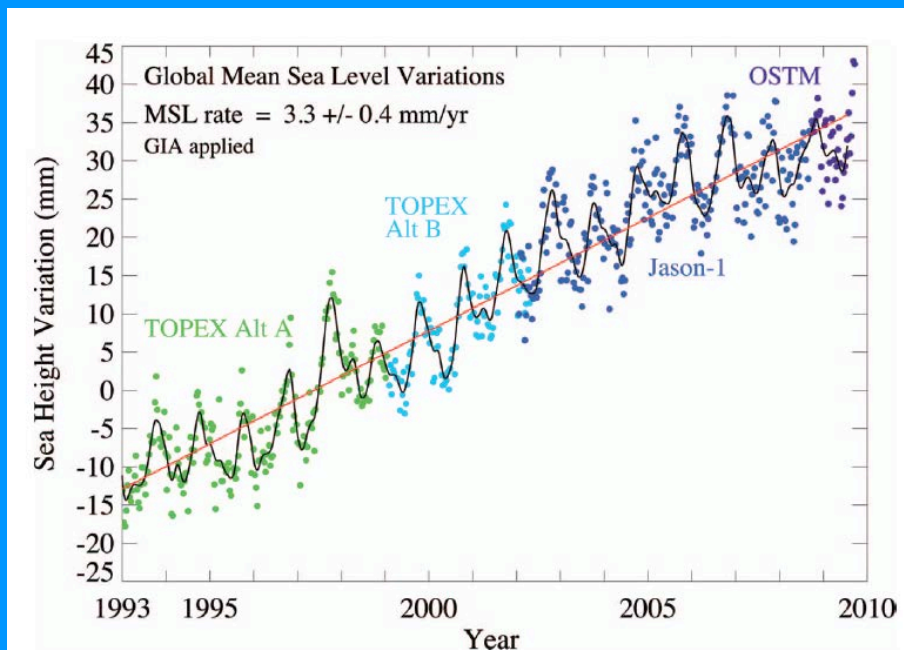
GPS, Kauai



GPS, Thule



Measurements of Global Mean Sea Level from Satellite Altimetry (TOPEX, Jason1, Jason2)

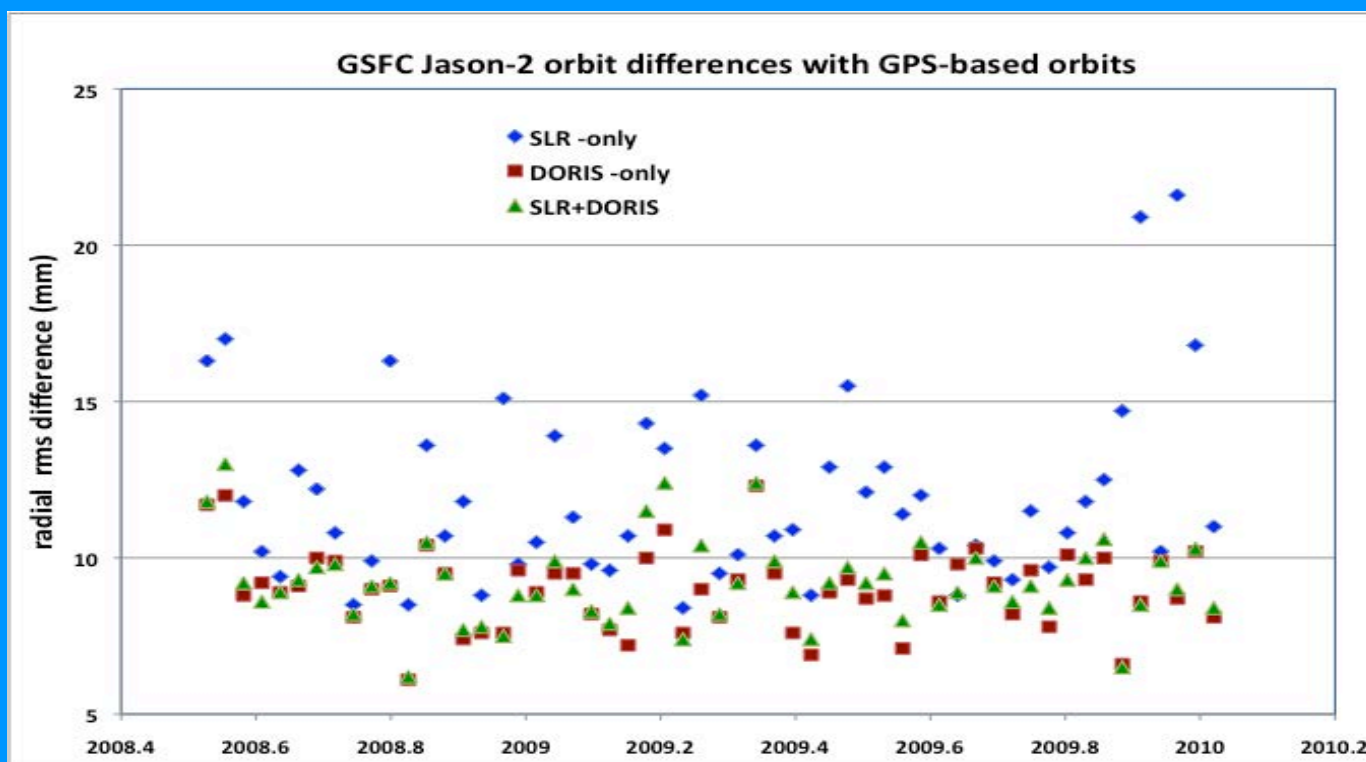


- GOT4.7 (tides)
- ITRF2005
- w/ TP & Jason radiometer corrections.

The determination of change in global mean sea level in the altimetry era (after 1993) is done with **SLR+DORIS** orbits in a consistent reference frame (ITRF2005). (Beckley et al., *Marine Geodesy*, 2010; Lemoine et al., *Adv. Space. Res.*, 2010)



For POD on the TOPEX/J1/J2 satellites, the Geodetic tracking from SLR, DORIS & GPS are Complementary & Synergistic



SLR + DORIS and DORIS-only orbits are superior to SLR-only orbits
(above example for Jason-2, but the same is true for Jason-1 and TOPEX).



Jason-2 Orbit Accuracy Validation

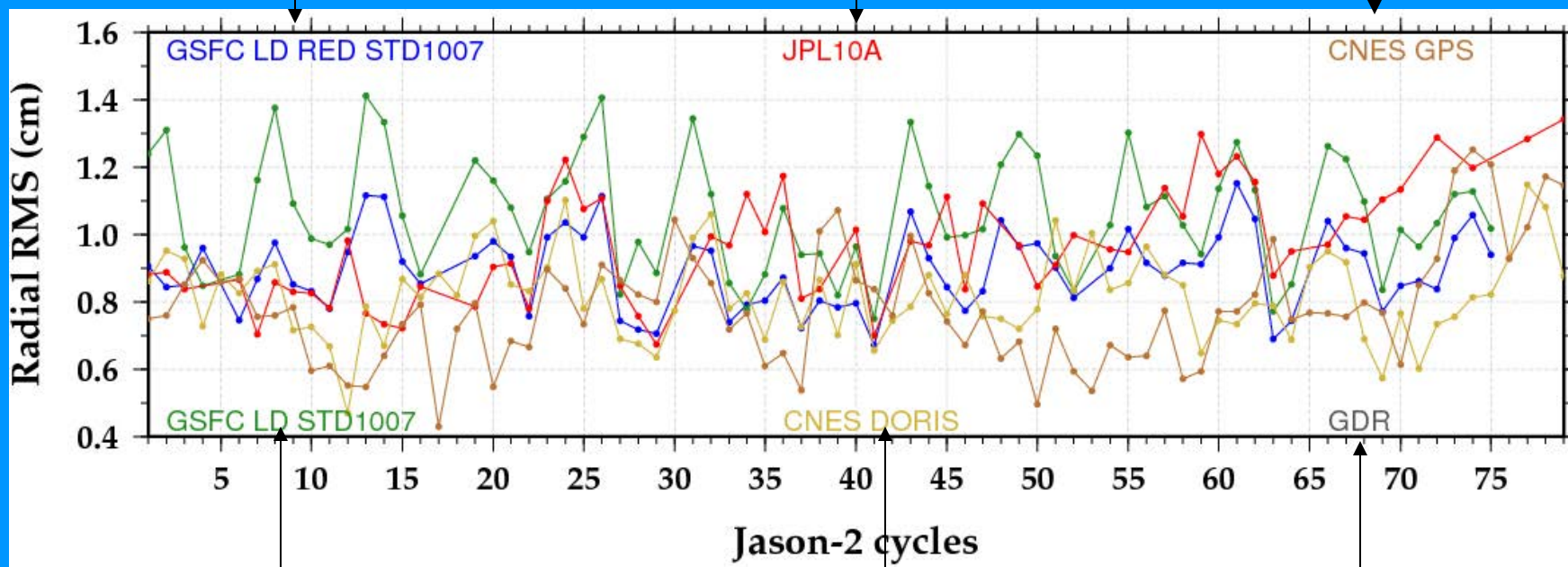


Jason-2 Orbit Intercomparisons using orbits computed with different geodetic data and based on different reference frame realizations) Allow Validation of Radial Orbit Accuracy. **HERE ALL ORBITS AGREE TO 1 cm radially.**

SLR+DORIS red-dyn (GSFC)

GPS-only red-dyn (JPL)

GPS-only (CNES)



SLR DORIS dyn. (GSFC)

DORIS-only (CNES)

SLR+DORIS+GPS (CNES)

Cerri et al. (2010)

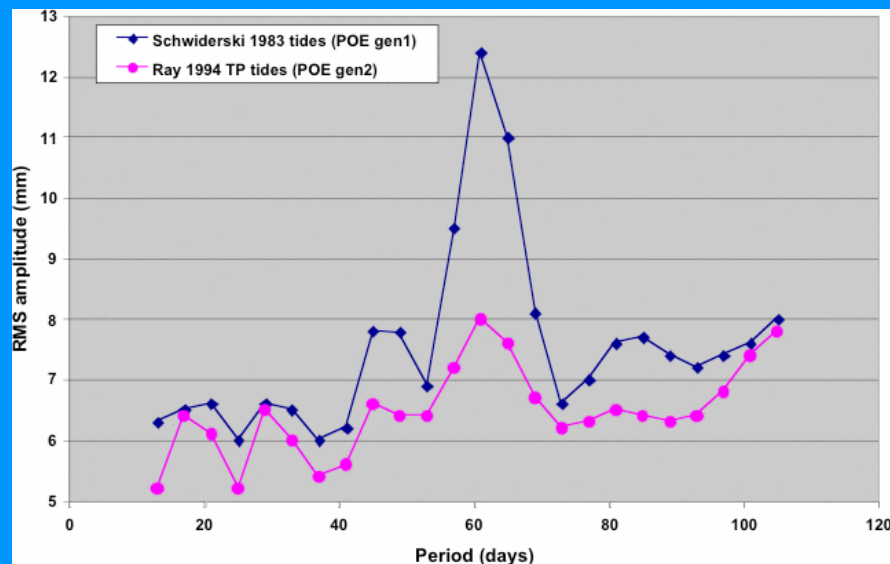
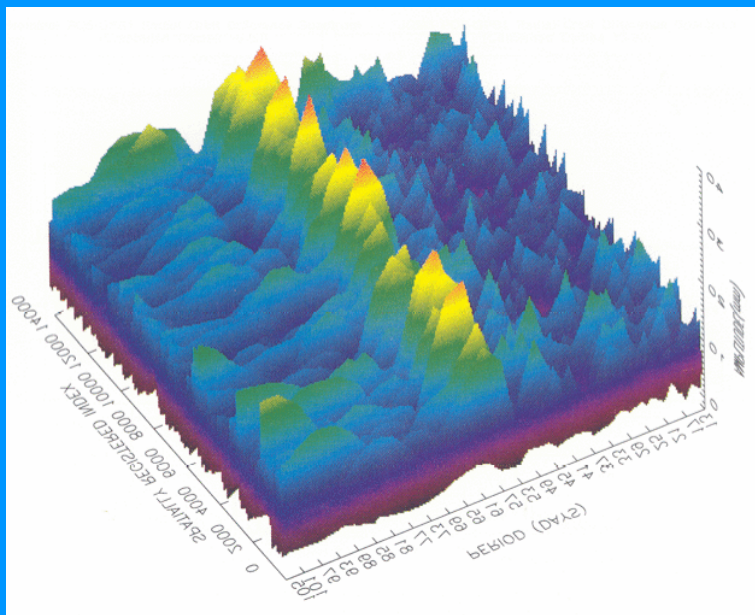


Intercomparison of Independent Orbits Produced by SLR/DORIS & GPS (Reduced Dynamic) allows insights into model and geodetic technique error And helps to validate improvements



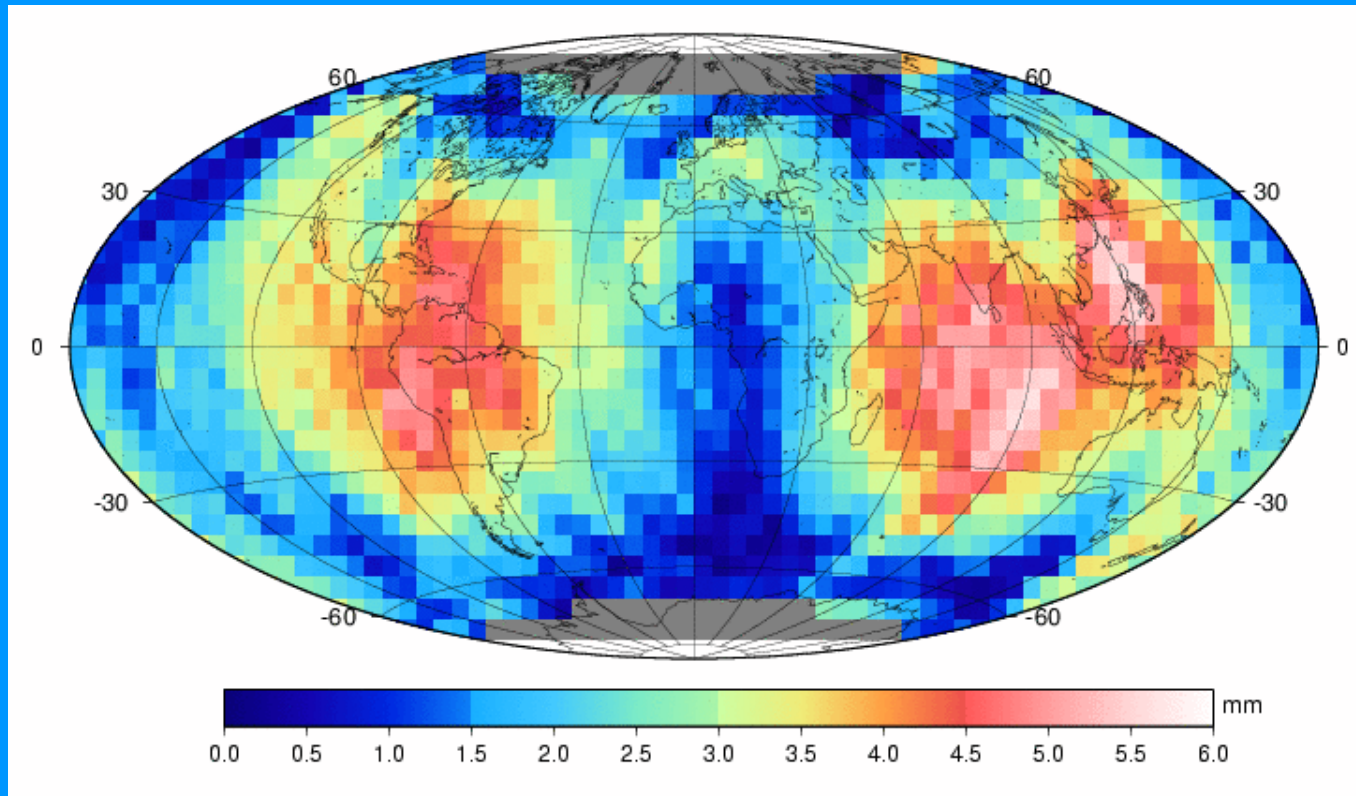
A priori (Schwiderski) Tide model produced orbit error at the M2 alias period (~60 days) for TOPEX

Tide model improvement using TOPEX altimeter data





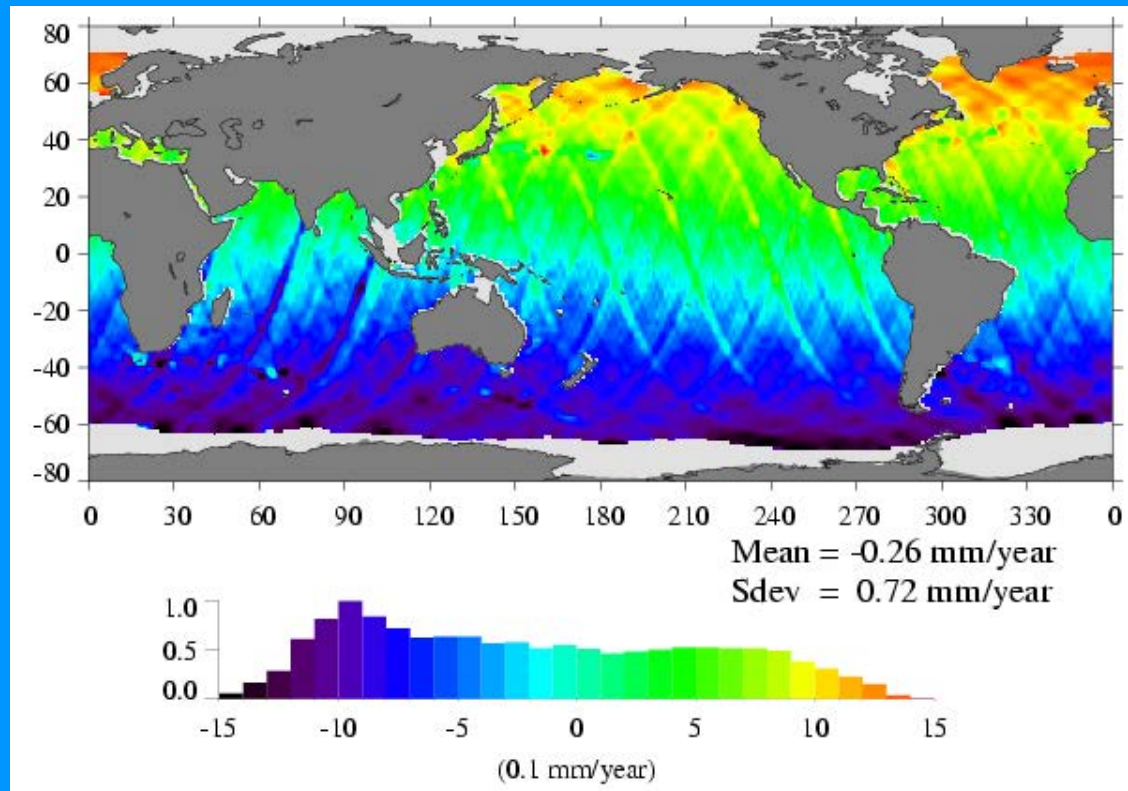
**Jason radial orbit 5-mm annual amplitude due to
time varying gravity (operational model from ECMWF
+ 20x20 annual from GRACE)**



By applying the time-varying gravity field of the atmosphere (to 50x50 every six hrs), and using annual variations in the geopotential to 20x20 derived from GRACE, we can improve POD on altimeter satellites such as Jason. SLR/DORIS orbits with/without this TVG model induce a radial annual variation in the orbits with an amplitude of 5 mm ... that would map into the altimetry or into station positioning (for DORIS).



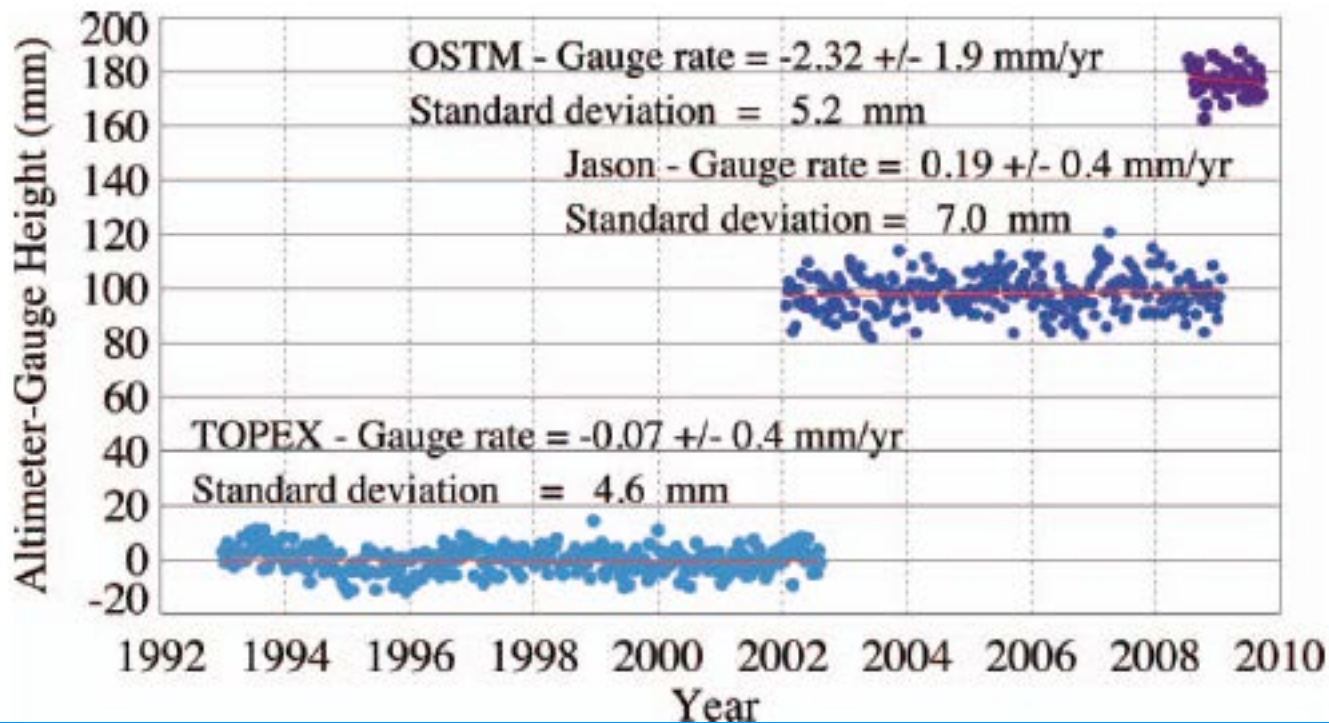
Impact of the Terrestrial Reference Frame on Mean Sea Level Determination



Regional **TOPEX (1993-2002)** Sea Surface Height Trend differences from direct impact of the **ITRF2005 (GGM02C)** minus **CSR95 (JGM3)** orbit differences. (from **Beckley et al., 2007**). Errors in the Z component of the TRF can produce large regional errors in MSL rate determination.



Application (example): Altimeter vs. tide-gauge calibration



GPS/DORIS/SLR enter into the determination of mean sea level in two ways:

1. (Directly) The orbit determination for the altimeter satellites (**TOPEX**, **Jason1**, **Jason2**)
2. (Indirectly) Determination of the vertical rates at some of the tide gauge sites.

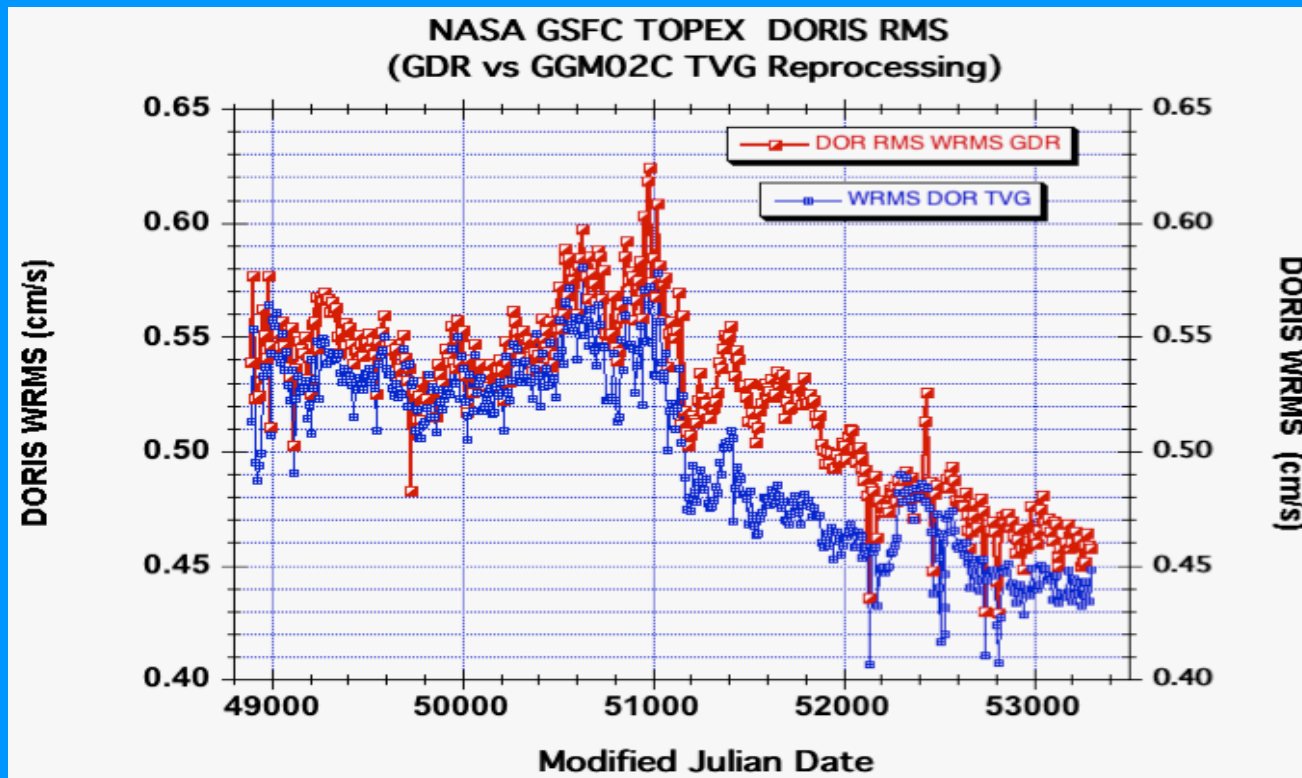
Monitoring the global average of the differences between sea level between altimetry data and the tide gauges allows us to monitor the performance of the altimeter system and guard against any instrumental drifts.



Synopsis of Some Recent Improvements ... Tracking System & Model Improvements (e.g.)



DORIS Evolution from TOPEX re-analysis



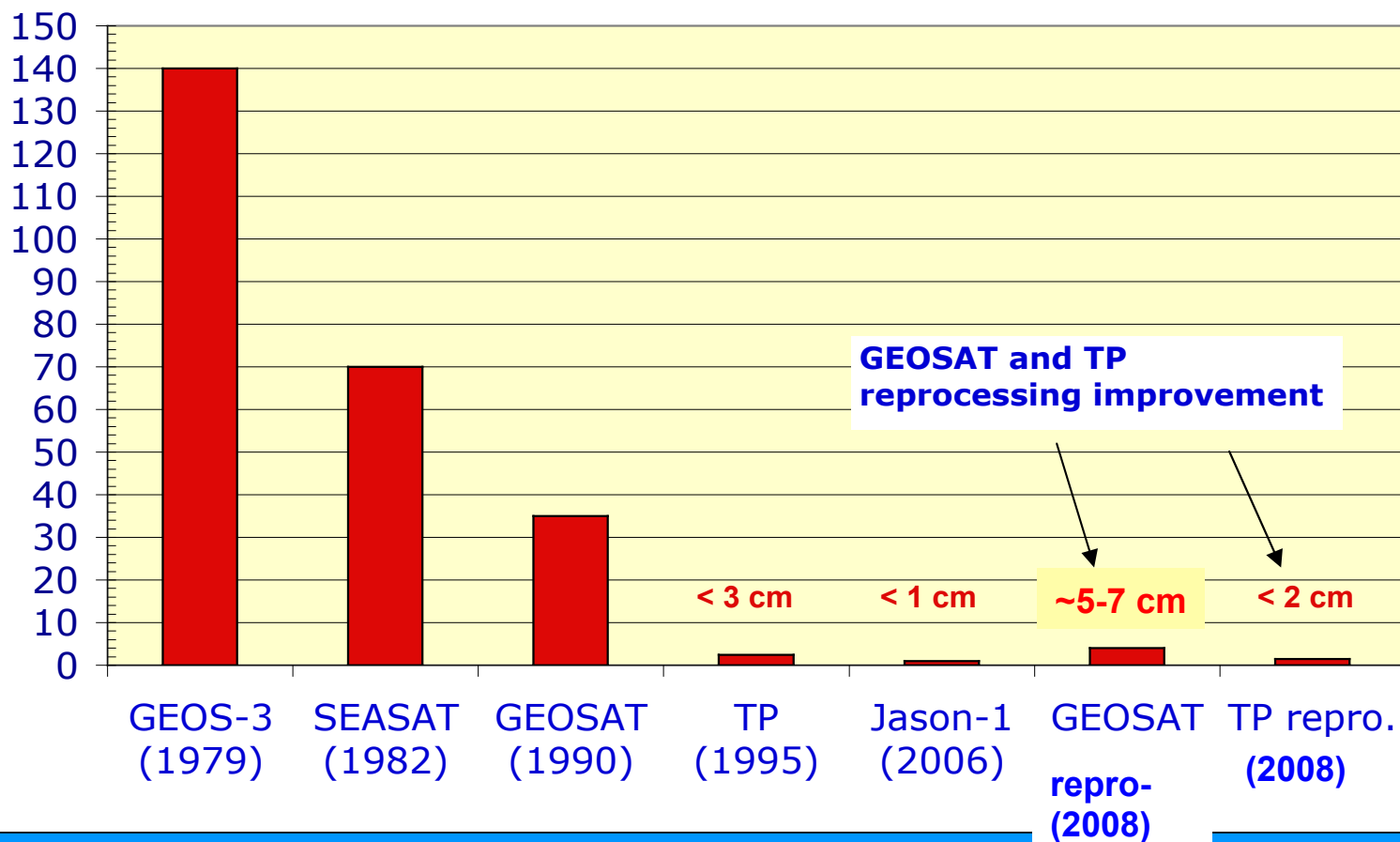
DORIS monument improvement and systematic application of site quality criteria significantly improved system performance (cf. Fagard, J. Geodesy, 2006). **Stable & precise monumentation is essential.**



Altimeter Satellite POD Summary



Radial Orbit Accuracy Achievement



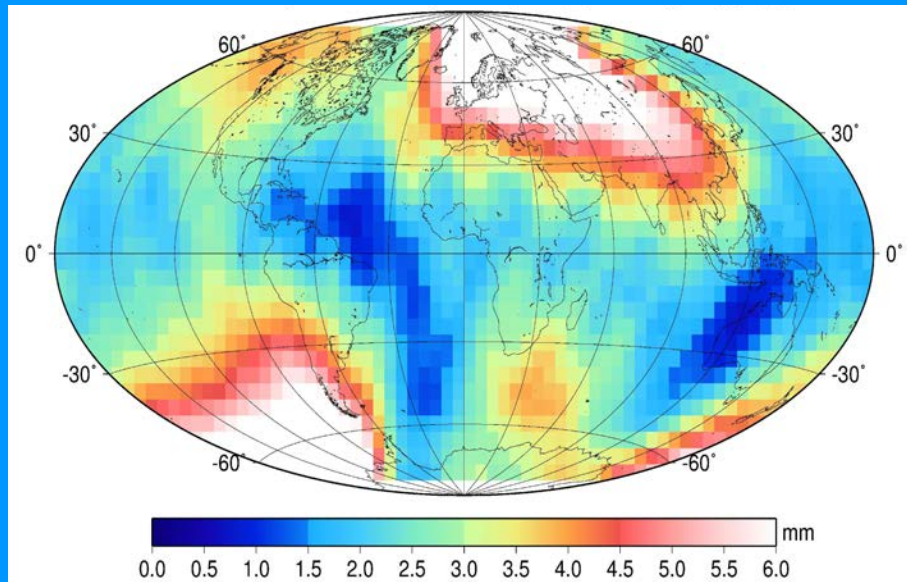


Continued Challenges



Radiation Pressure Modelling:

e.g., SLR/DORIS ($C_R=1$) – JPL GPS6b orbits, 120-day amplitude for Jason-1



1. Providing a consistent orbit time series for altimeter data over 16+ years, spanning three missions, and four altimeters - to better resolve interdecadal signals & MSL change.
2. Radiation Modelling Improvements.
3. Reference Frame Stability.
4. Measurement model improvements for SLR, GPS & DORIS.
5. Geocenter.
6. Deployment of Next Generation Geodetic Stations (SLR, GPS).



Altimeter Satellite Status & Future Missions



JASON-1 (CNES, NASA), 2002	1336 km, 66°	D2G + SLR + GPS
JASON-2 (NASA, CNES), 2008	1336 km, 66°	DGXX + SLR + GPS
CRYOSAT-2 (ESA), April 2010	717 km, 92°	DGXX + SLR
ENVISAT (ESA), 2002	~800 km, 98.5°	D2G + SLR
HY2A (CNSA), (Launched August 2011; Then HY2B, HY2C)	963 km, 99.3°	DGXX + SLR + GPS
<hr/>		
SARAL/ALTIKA (ISRO/CNES) (Launch: 2012)	880 km, 98.5°	DGXX + SLR
SENTINAL 3A (GMES) (Launch: April 2013)	814 km, 98.6°	DGXX + SLR + GPS
JASON-3 (NASA/NOAA/CNES/EUMETSAT)(2014; Follow-on to TOPEX, Jason-1, Jason-2)	1336 km, 66°	DGXX + SLR + GPS
ICESAT-2 (NASA, Laser altimeter) (Launch ~2015)		GPS + (SLR)
SWOT (CNES, NASA) (Surface Water Ocean Topography; Launch 2018-2020)	970 km, 78°	DGXX + SLR + GPS



Obrigado. Thank you for your attention.

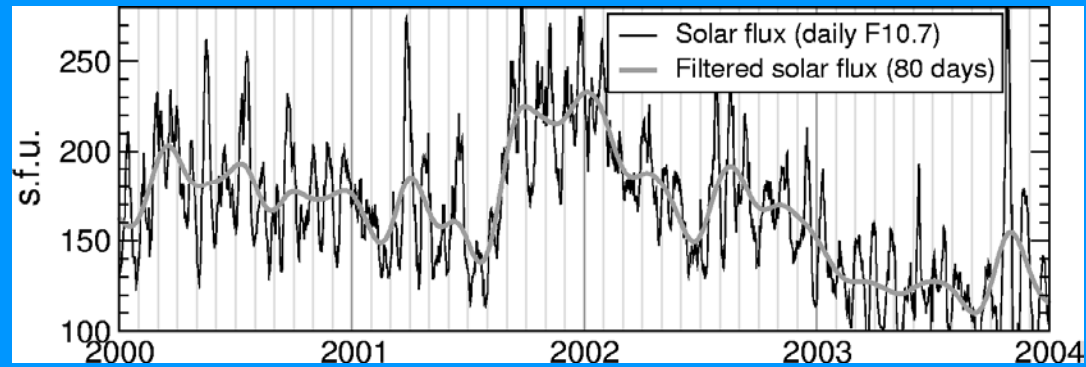


(Some) Reference Frame Issues (3)

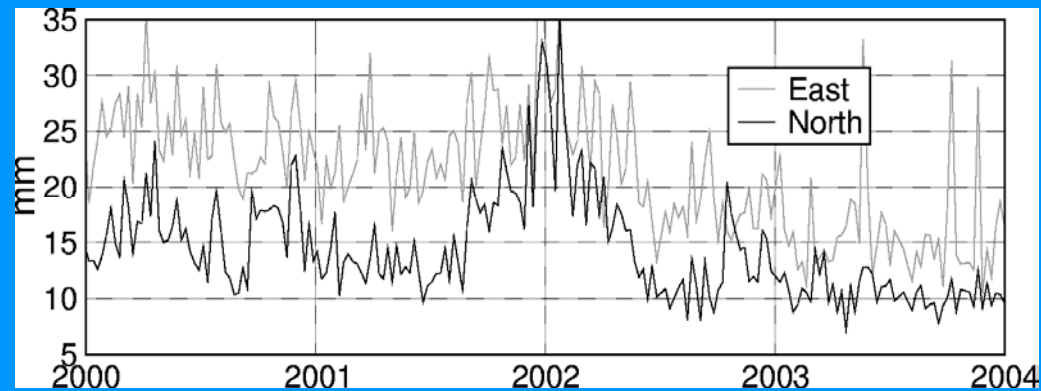
DORIS Station Determination affected by Atmospheric Drag Increase near Solar maximum



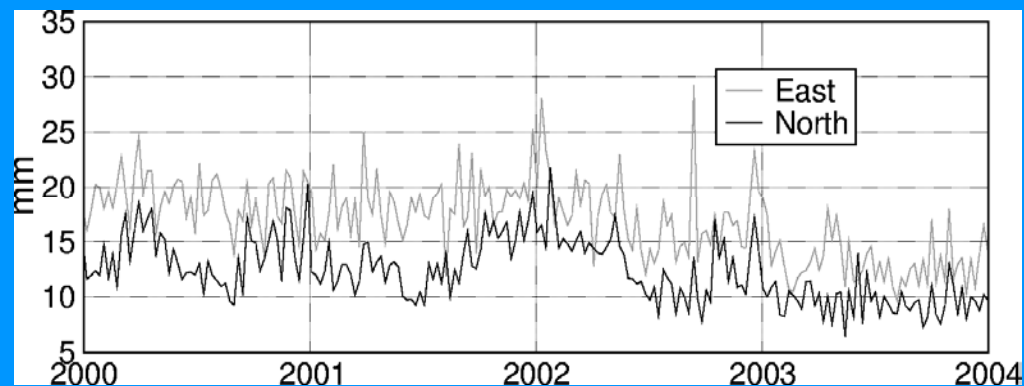
Solar Flux



IDS-1
Horizontal Residuals



IDS-3
Horizontal Residuals



Valette et al., 2010.